# THE SYSTEM FOR ACOUSTIC SCENE CLASSIFICATION USING RESNET

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# ABSTRACT

In this report, we present our works concerning task 1a of DCASE 2019, i.e. acoustic scene classification (ASC) with mismatched recording devices. We propose a strategy of classifiers voting for ASC. Specifically, an audio feature, such as logarithmic filter-bank (LFB), is first extracted from audio recordings. Then a series of convolutional neural network (CNN) is built for obtaining classifiers ensemble. Finally, classification result for each test sample is based on the voting of all classifiers.

*Index Terms*—convolutional neural network, acoustic scene classification, classifiers voting

### **1. INTRODUCTION**

ASC is a process of determining a test audio recording belongs to which pre-given class of acoustic scenes, it can be regarded as the same task of audio representation and classification and tackled by using the same feature and classifier. It is useful for multimedia retrieval [1], audiobased surveillance and monitoring [2, 3]. What's more, they are under great attention of the research community with many evaluation campaigns [4-8], and are not effectively solved due to large variations of time-frequency characteristics within each class of sound events and acoustic scenes, non-stationary background noises, overlapping of sound events, and so forth [9].

The overall performance of audio classification system mainly depends on two stages: feature extraction and classifier building. Almost all of recent studies focused on these two stages for achieving better performance [10]. Many systems were submitted to the previous DCASE challenge for ASC, and some of them achieved satisfactory results. They were based on the combinations of various features with different classifiers. The features include MFCCs, log Mel-band energy, spectrogram, Gabor filterbank, pitch, time difference of arrival, amplitude modulation filterbank, while the classifier mainly consists of Gaussian mixture model, Deep Convolutional Neural Network(DCNN), RNN, time-delay neural network, logistic regression, random forest, decision tree, gradient boosting, support vector machine, hidden Markov model.

In our submissions for task 1b of DCASE 2019, we perform ASC using a strategy of classifiers voting. The rest of this report is organized as follows. Section 2 describes the proposed method and Section 3 and 4 present experiments and results. Finally, conclusions are drawn in Section 5.

### 2. THE METHOD

The proposed framework for ASC is depicted in Fig. 1, which mainly consists of two modules: feature extraction and CNN classification. For task 1 (i.e. ASC), the audio recordings of each acoustic scene are fed into the system and the labels of acoustic scene are output by the system.

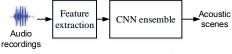


Fig. 1. The proposed system for ASC.

Many kinds of CNN structures, such as VGG, Inception, Resnet, have generated from image classification [11] and they obtained good results for image classification due to the CNN's strength on catching difference of various feature maps. These popular CNN structures were popularly used audio classification [12]. Only one type of CNN structure was adopted for audio classification instead of a combination of many CNN structures. Although each kind of CNN structure shows powerful ability of classification, they still have unique characteristics[13]. If they are fused in an effective way, we can obtain a stronger ASC system. Hence, we try to combine CNNs to make classification decisions.

#### **3. EXPERIMENTS**

Our experiments are mainly performed on the TensorFlow.We extracted LFB feature from raw audio datasets. The detail of the parameter can be listed as Table1. And the structure of ResNet is showed as Fig. 2.

Table 1 Parameter settings for extracting LFB.

feature	frame length/overlap	dimension	channel	feature matrix
				shape
LFB	50/20 ms	80	mono+binaural	(499,80,3)

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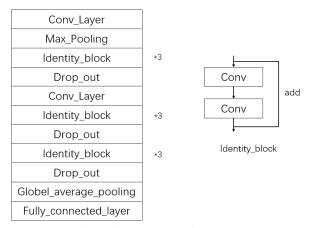
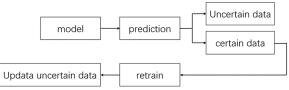


Fig. 2 The structure of ResNet.

We divided the development datasets into four parts, then compute the mean and variance of each parts. Then we use the mean and variance in the development set, so we can get 4 different training set. We extracted LFB features from each training set. Next we put the data to model, and the model is ResNet. While the training was ended, we can get 4 models. So we can get 4 results after we use the model to predict the label of evaluate dataset. Finally, we use these results to vote to produce a final results. At the first step of prediction, we get the prediction result of every model, and vote for the 10 scenes classification. From the vote results, we take the most votes as the final result. At the second step of predict, we consider a result as a uncertain prediction that get the most votes but its' votes is very close to second place, similarly, If most votes far more than second place, we consider the prediction as a certain result. So we divide our prediction into two parts, for the certain part, we fed into our model to retrain. At the third step of prediction, we vote again with the retraining model of step2, and renew the uncertain part of result. The process can be seen in Fig. 3.



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#### Fig. 3 Processing of prediction

#### 4. EXPERIMENTS

Table 1 shows the experiment results and Table 2 shows accuracy of per scene. In all results, it exceeds the accuracy of Baseline system. Also, by taking the voting method of all models, you can see that the accuracy is greatly improved, and the retraining make further improvement.

Table 1 Classification results.					
Models	Accuracy (%)	Accuracy (%)			
Widdels	(Development)	(Leaderboard)			
Baseline	62.5	64.3			
Resnet	89.7	75.33			
Vote	93.0	78.33			
Retain and vote	_	79.66			
again					

Table 2 Audio classification accuracy per scene.

Tuble 2 Huulo	Table 2 Madio classification accuracy per sectio.				
Scene label	Baseline (%)	Proposed (%)			
Airport	48.4	82.3			
Bus	62.3	65.5			
Metro	65.1	74.2			
Metro station	54.5	62.5			
Park	83.1	55.7			
Public square	40.7	57.8			
Shopping mall	59.4	66.2			
Street, pedestrian	60.9	75.6			
Street, traffic	86.7	82.3			
Tram	64.0	85.3			
Average	62.5	74.7			

#### 4. CONCLUSIONS

We described how to identify acoustic scenes using multiple spectrogram. In addition, we propose a voting mechanism to divide voting results into certain part and uncertain part, and utilize certain prediction to pretrain and finetune original model to adapt to test datasets. As a result, we improve accuracy of leaderboard.

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